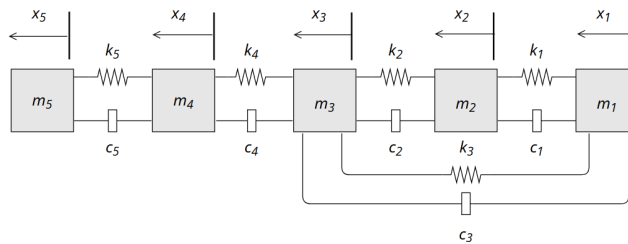






a. a(a) a & ž a %



$$L = T - V$$

$$\frac{d}{dt} \left(\frac{\partial L}{\partial \dot{x}_i} \right) - \frac{\partial L}{\partial x_i} = Q_i$$

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E

$$\{\ddot{x}\} + [M]^{-1}[C]\{\dot{x}\} + [M]^{-1}[K]\{x\} = [M]^{-1}\{F\}$$

$$[M] = \begin{bmatrix} m_1 & 0 & 0 & 0 & 0 \\ 0 & m_2 & 0 & 0 & 0 \\ 0 & 0 & m_3 & 0 & 0 \\ 0 & 0 & 0 & m_4 & 0 \\ 0 & 0 & 0 & 0 & m_5 \end{bmatrix} \quad [K] = \begin{bmatrix} k_1 + k_3 & -k_1 & -k_3 & 0 & 0 \\ k_1 & k_1 + k_2 & -k_2 & 0 & 0 \\ -k_3 & -k_2 & k_2 + k_3 + k_4 & -k_4 & 0 \\ 0 & 0 & -k_4 & k_4 + k_5 & -k_5 \\ 0 & 0 & 0 & -k_5 & k_5 \end{bmatrix}$$



$$[C] = \begin{bmatrix} c_1 + c_3 & -c_1 & -c_3 & 0 & 0 \\ c_1 & c_1 + c_2 & -c_2 & 0 & 0 \\ -c_3 & -c_2 & c_2 + c_3 + c_4 & -c_4 & 0 \\ 0 & 0 & -c_4 & c_4 + c_5 & -c_5 \\ 0 & 0 & 0 & -c_5 & c_5 \end{bmatrix} [F] = \begin{bmatrix} F_p \\ 0 \\ F_p \\ F_p \\ F_{medic} \end{bmatrix} [x] = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \end{bmatrix}$$

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$$x_m = \begin{bmatrix} x \\ \dot{x} \end{bmatrix}$$

$$\dot{x}_m = A_m x_m + B_m F_m$$

$$A_m = \begin{bmatrix} 0_{5 \times 5} & I_{5 \times 5} \\ -M^{-1}K & -M^{-1}C \end{bmatrix} B_m = \begin{bmatrix} 1/m_1 & 0 & 1/m_3 & 1/m_4 & 0 & 0_{1 \times 5} \\ 0 & 0 & 0 & 0 & -1/m_5 & 0_{1 \times 5} \end{bmatrix} F_m = [F_P]$$

E A_{5G}

D

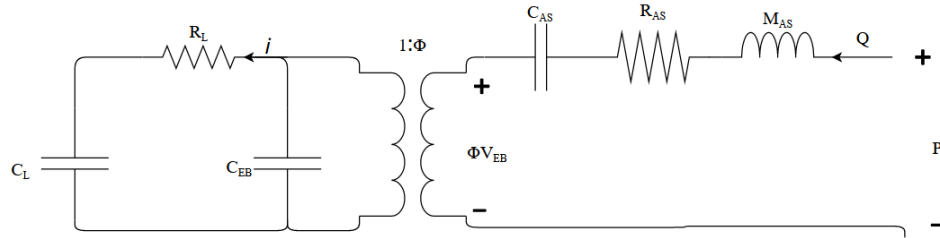
7_{5G}

F_{5G}

7₉₆

F_@

7_@



J₉₆

7_@ 7₉₆

F_@

$$\dot{V}_{EB} = R_L \frac{di}{dt} + \left(\frac{1}{C_L} + \frac{1}{C_{EB}} \right) i$$

J₉₆

$$\frac{di}{dt} = \frac{\Phi}{R_L C_{EB}} Q - \frac{1}{R_L} \left(\frac{1}{C_L} + \frac{1}{C_{EB}} \right) i$$

$$\ddot{Q} = -\frac{1}{M_{AS}} \left(\frac{\phi^2}{C_{EB}} + \frac{1}{C_{AS}} \right) Q - \frac{R_{AS}}{M_{AS}} \dot{Q} + \frac{\phi}{M_{AS} C_{EB}} i + \frac{\dot{P}}{M_{AS}}$$

7_{5G} A_{5G} F_{5G} X₅

k f

W

g

$$\frac{dN_r}{dr} + \frac{N_r - N_\theta}{r} = 0$$

$$Q_r = \frac{dM_r}{dr} + \frac{M_r - M_\theta}{r}$$

A B_f B

E_f

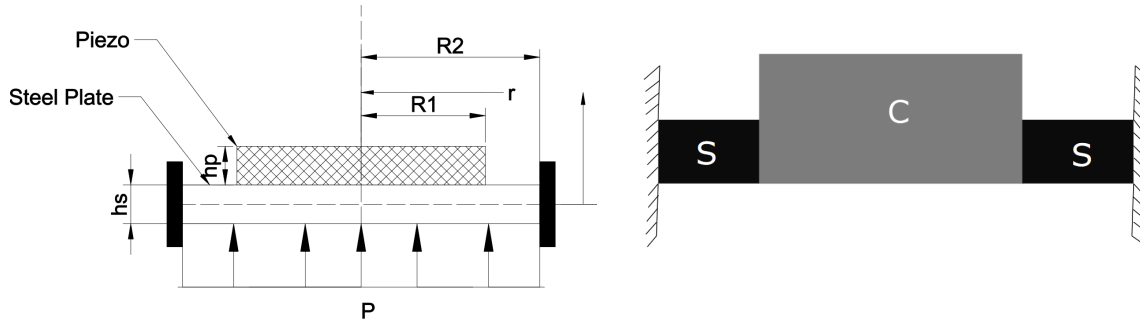
A_f

D

$E_f 1$ —

i f

f



$$\frac{d^2\theta}{dr^2} + \frac{1}{r} \frac{d\theta}{dr} - \frac{\theta}{r^2} = -\frac{Q_r}{D_{11}^r}$$

$$\frac{d^2u}{dr^2} + \frac{1}{r} \frac{du}{dr} - \frac{u}{r^2} = -\frac{Q_r \alpha}{D_{11}^r}$$

— 8^f%

f

$$w^c(r) = c_1^c \left(\frac{r^2 - R_2^2}{2} \right) - \frac{P(r^4 - R_1^4)}{64D_{11}^{r(c)}} + c_1^s \left[\frac{R_1^2 - R_2^2}{2} - R_2^2 \ln\left(\frac{R_1}{R_2}\right) \right] + \frac{P}{64D_{11}^{(s)}} \left[4R_2^4 \ln\left(\frac{R_1}{R_2}\right) - R_1^4 + R_2^4 \right]$$

$$w^s(r) = c_1^s \left[\frac{r^2 - R_2^2}{2} - R_2^2 \ln\left(\frac{r}{R_2}\right) \right] + \frac{P}{64D_{11}^{(s)}} \left[4R_2^4 \ln\left(\frac{r}{R_2}\right) - r^4 + R_2^4 \right]$$

$$x_c = \begin{bmatrix} x_m \\ x_e \end{bmatrix}$$



$$\dot{x}_c = A_c x_c + B_c F_m$$

$$V = C_c x_c$$

J

$$A_c = \begin{bmatrix} A_m & 0_{8 \times 3} \\ B_e C_m A_m & A_e \end{bmatrix} \quad B_c = \begin{bmatrix} B_m \\ B_e C_m B_m \end{bmatrix} \quad C_c = [0_{1 \times 8} \quad C_e]$$

$$x_e = \begin{bmatrix} Q \\ \dot{Q} \\ i \end{bmatrix} \quad A_e = \begin{bmatrix} 0 & 1 & 0 \\ -\frac{1}{M_{AS}} \left(\frac{\phi^2}{C_{EB}} \frac{1}{C_{AS}} \right) & -\frac{R_{AS}}{M_{AS}} & \frac{\phi}{M_{AS} C_{EB}} \\ \frac{\Phi}{R_L C_{EB}} & 0 & -\frac{1}{R_L} \left(\frac{1}{C_L} + \frac{1}{C_{EB}} \right) \end{bmatrix} \quad B_e = \begin{bmatrix} 0 \\ \frac{1}{M_{AS}} \\ 0 \end{bmatrix}$$

$$C_e = [0 \quad 0 \quad R_L] \quad C_m = \frac{1}{A_s} [k_1 \quad -k_1 \quad 0 \quad 0 \quad 0 \quad c_1 \quad -c_1 \quad 0 \quad 0 \quad 0]$$

J

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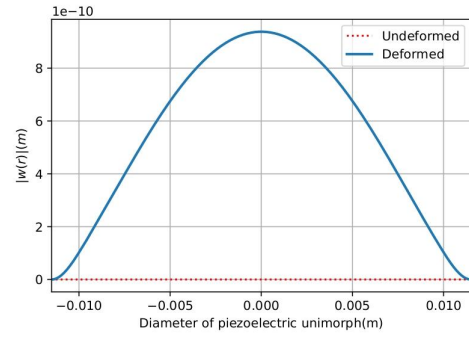
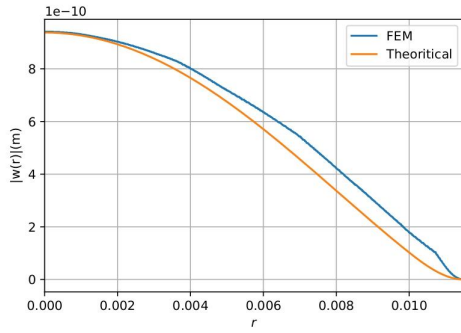
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